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# **TSV-OCT**: An on-communication multiple-TSV defects detection and localization for 3D-ICs

Technical Presentations

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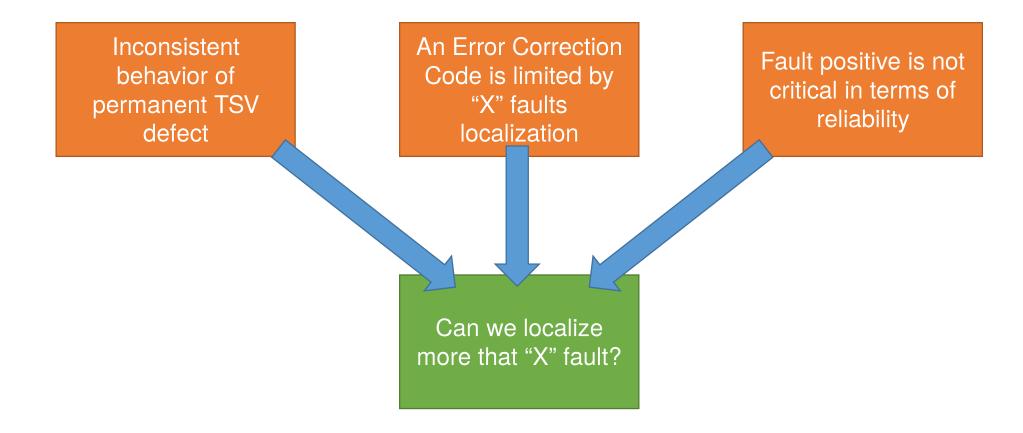
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## Summary





Fault positive: a device is healthy but it was determined as faulty

## Content



- > Introduction
- Proposed architecture
- > Evaluation
- Conclusion

## Content

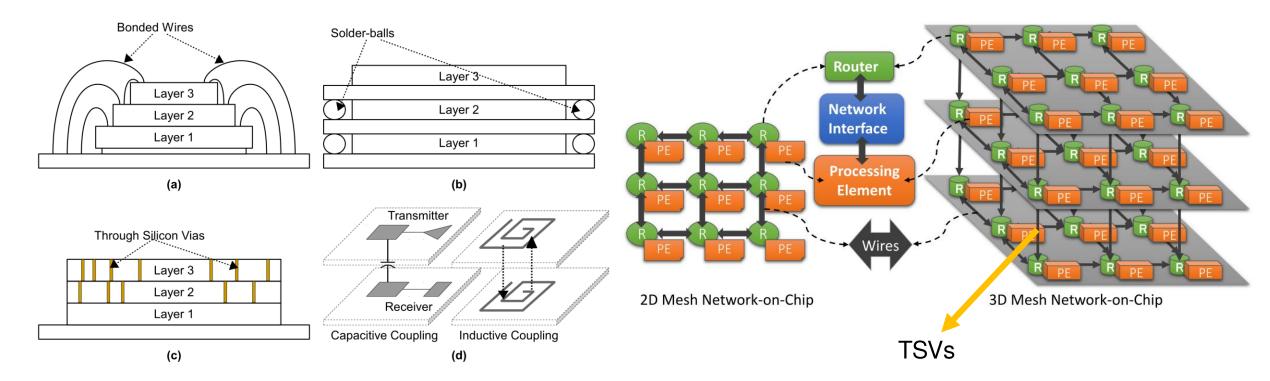


## > Introduction

- Proposed architecture
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### Toward the 3D-ICs





3D Integration technologies: (a) Wire bonding; (b) Solder balls; (c) Through Silicon Vias (TSVs); (d) Wireless stacking.

3D Mesh Network-on-Chip to utilize TSVs as vertical links

To keep up with the increase of integration density, moving to the third dimensions could be an promising solution

One of the most mature near-future technology is TSV (Through Silicon Via)

## TSV Reliability Issue



### Despite of several advantages, TSVs also have several reliability issues:

- The yield rate is low due to imperfect manufacturing processes.
- Cross-talk issues:
  - Because TSVs run in parallel, cross-talk is a common issue
- Vulnerable to thermal stress:
  - Difference in thermal expansion coefficients of materials.
  - The difference in layers' temperature could lead to crack/misalignment on TSV.
- Higher operating temperature:
  - Thermal dissipation become more difficult in 3D-ICs
    - Higher layers receive heat from bottom layers
    - TSV as heatsink or micro flood cooling is still immature

## To solve the reliability issue



### Testing:

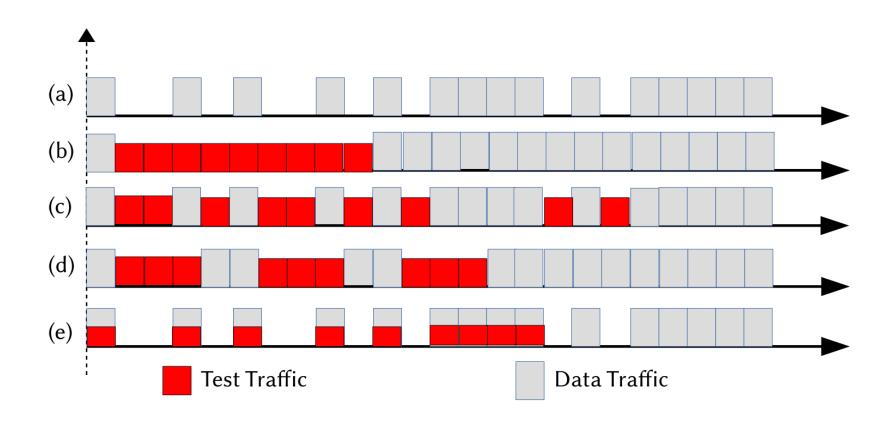
- Built-in-Self-Test, external testing, online testing:
  - For on-line, periodical BIST could be used.
- Error Correction/Detection Code
  - For example: SECDED, OLSC, ...

### Recovery:

- Hardware tolerance: Redundancies, Re-mapping
- Information redundancies: coding, re-transmission
- Algorithm based: fault-tolerant routing

## Online testing tratergies





The sequence of data and test traffic under different strategies: (a) application traffic;
 (b) block test; (c) free time test traffic injection; (d) split free time test; (e) on-communication test.

### Error Correction Code localization limitation



- In coding theory, a code C is said to be *k* error correcting (fault localization) if the minimum Hamming distance between two code word is at least 2k+1.
- Using ECCs for fault detection and localization is possible, but limited by number of faults.
  - Extended Hamming code: 1 fault correction/localization, 2 fault detections
  - Orthogonal Latin Square code: m\*m data bit with 2mt parity bit (t<m) could correct t faults.
- If we can improve ECCs by increasing localization ability, we could obtain:
  - Non-blocking test
  - No performance degradation
  - Fast execution time.

### Contributions



In this paper, we propose a novel method named On-communication TSV Test (OCTT) which is specially designed for correcting and detecting faults in TSV-based links:

- A comprehensive set of algorithm including: Statistical Detection and Isolation-end-Check.
- Statistical Detection take the outputs of ECC and mark the suspicious positions
- *Isolation-end-Check* reconfirms the suspicious positions as healthy or faulty.

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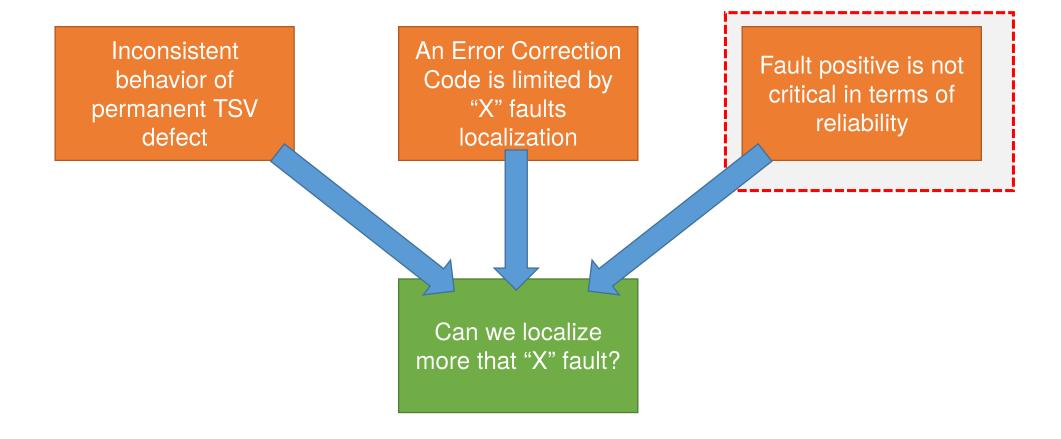


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## Proposed method



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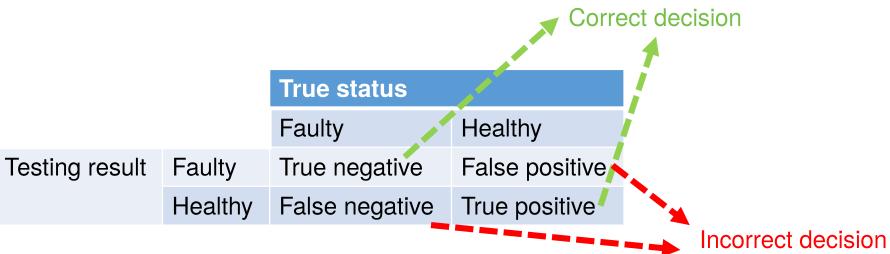


Fault positive: a device is healthy but it was determined as faulty

## Testing accuracy



- In testing, there are four major cases.
  - False negative is the critical case: the device is faulty but the testing process determine it as healthy.
  - The false positive case is less critical.
- For ECCs, since it works in parallel with the communication (no interruption and no performance degradation):
  - The communication still perform as usual.
  - False positive is non critical.

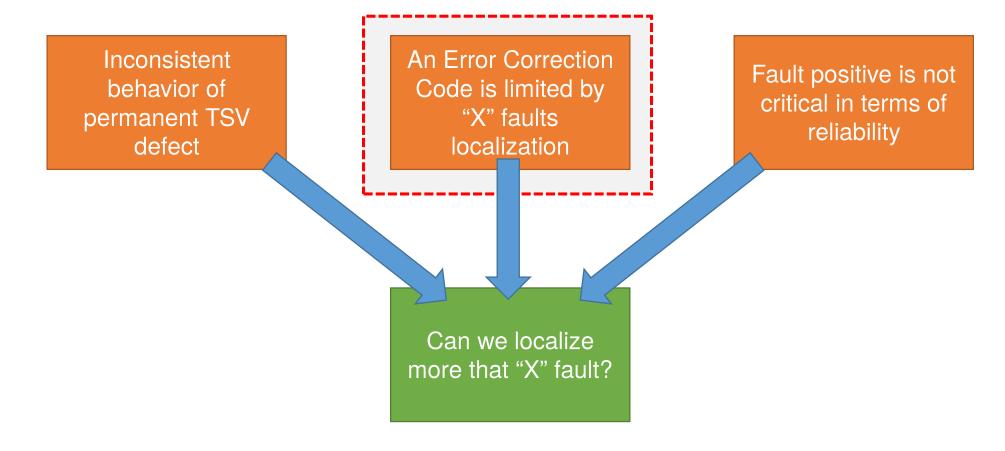


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## Proposed method



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Fault positive: a device is healthy but it was determined as faulty

## Baseline Parity Product Code

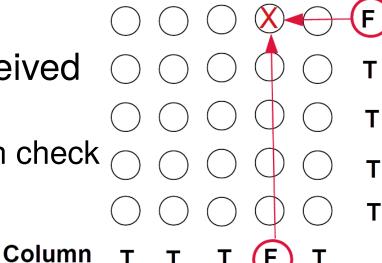


Row

check

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- A TSV-based connection are organized in a group MxN data bit which is encoded into (M+1)(N+1) code-word bit.
- Parity bits are:
  - Row parity bits
  - Column parity bits
  - All bit parity
- When a flit of (M+1) rows (N+1) columns are received ○○○
  - Check row parity and column parity
  - Faulty position has faulty row check and faulty column check
- Parity product code (PPC) can:
  - Localize/correct one fault
  - Detect two faults



check

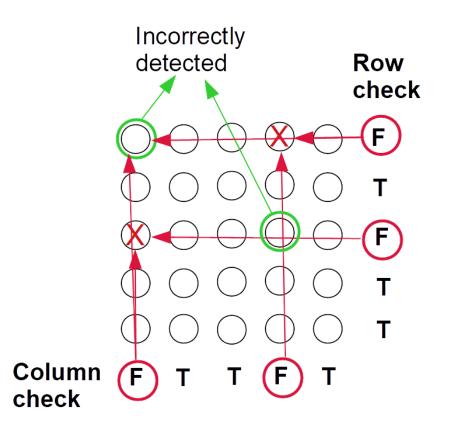
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### Fault detection: 2+ faults



- If there is two or more faults, there is a chance of detection:
  - If there is 2+ faulty row check, or 2+ faulty column check, there are multiple faulty bit
- If we consider the localization:
  - Red X: true negative
  - Green circle: false positive
- Can we remove the false positive case?

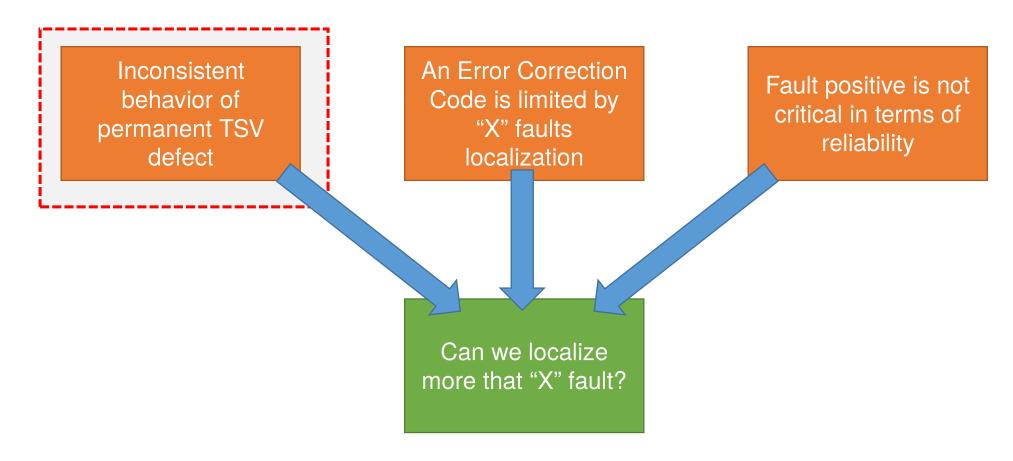
		True status			
		Faulty	Healthy		
Testing result	Faulty	True negative	False positive		
	Healthy	False negative	True positive		



## Proposed method



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Fault positive: a device is healthy but it was determined as faulty

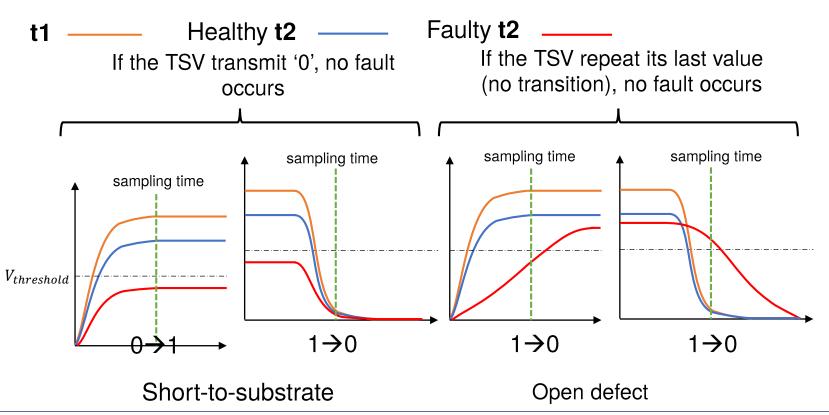
### Fault model

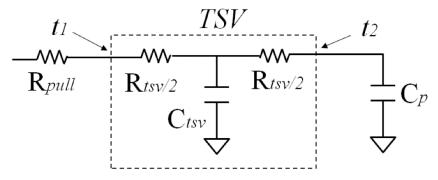


#### The TSV defects are modeled as:

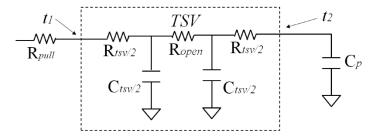
- Short-to-substrate: the value of TSV is stuck at '0'.
- Open: slow down the transition of TSV, delay the value of TSV by one clock cycle.

#### → Hidden fault could happen during operation

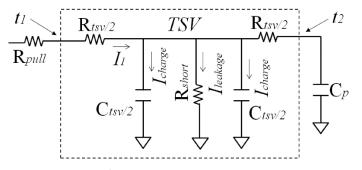




#### Normal TSV



#### Open defect



#### Short-to-substrate

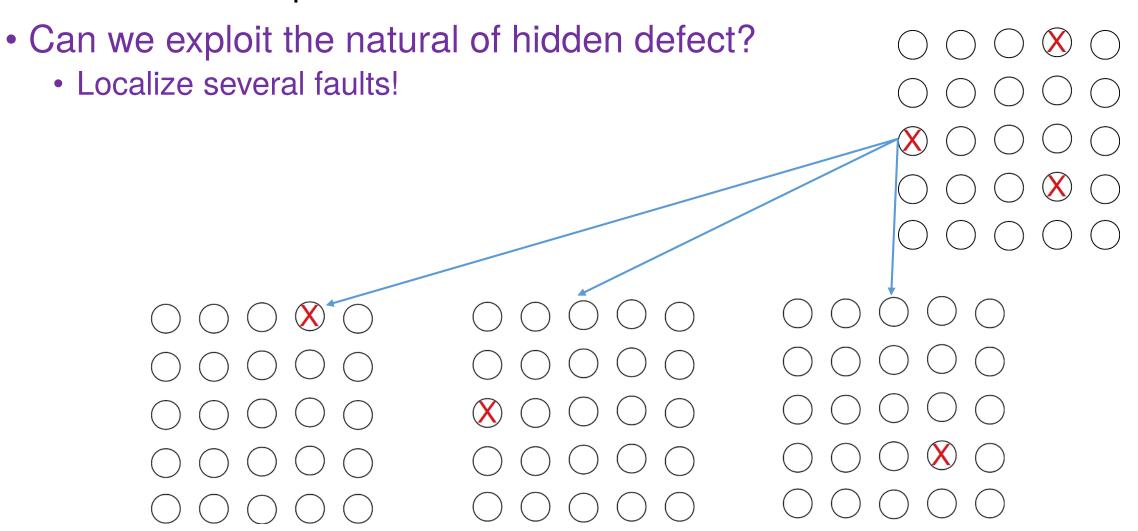
Y. Zhao et al., "Online Fault Tolerance Technique for TSV-Based 3-DIC," IEEE Trans. VLSI Syst., vol. 23, no. 8, pp. 1567–1571, 2015.

### Hidden defects



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• Because of the hidden defects, we could observe the inconsistency of the ECC correction patterns

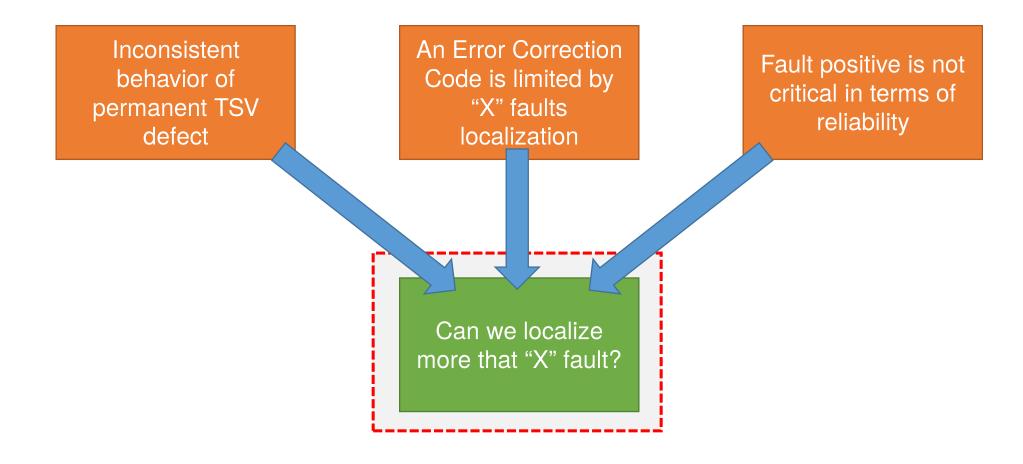


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## Proposed method



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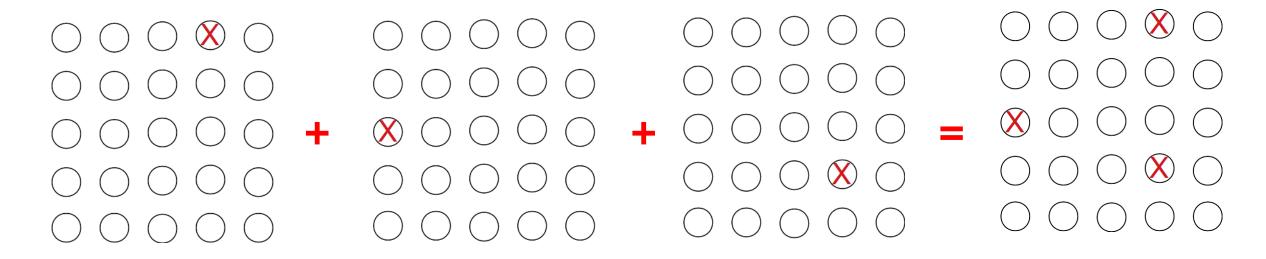


Fault positive: a device is healthy but it was determined as faulty

### Statistical detection: cautious localization



- Perform ECC in T cycles (period) to capture as much as possible:
- If there is only one fault occurrence, we could accumulate the result!



Catch 1 Catch 2 Catch 3

Final

• By cautiously capture single fault localization, a single error correction coding technique could localize more than one fault.

## Statistical Detection (continue)



- Perform PPC in several cycle to capture as much as possible:
- With two or more defect occurrences, there are false positive cases
  - If we are cautious, just skip this case and wait until on fault left
- However, if there is multiple faults, we "cannot" wait:
  - Let be greedy!







80000



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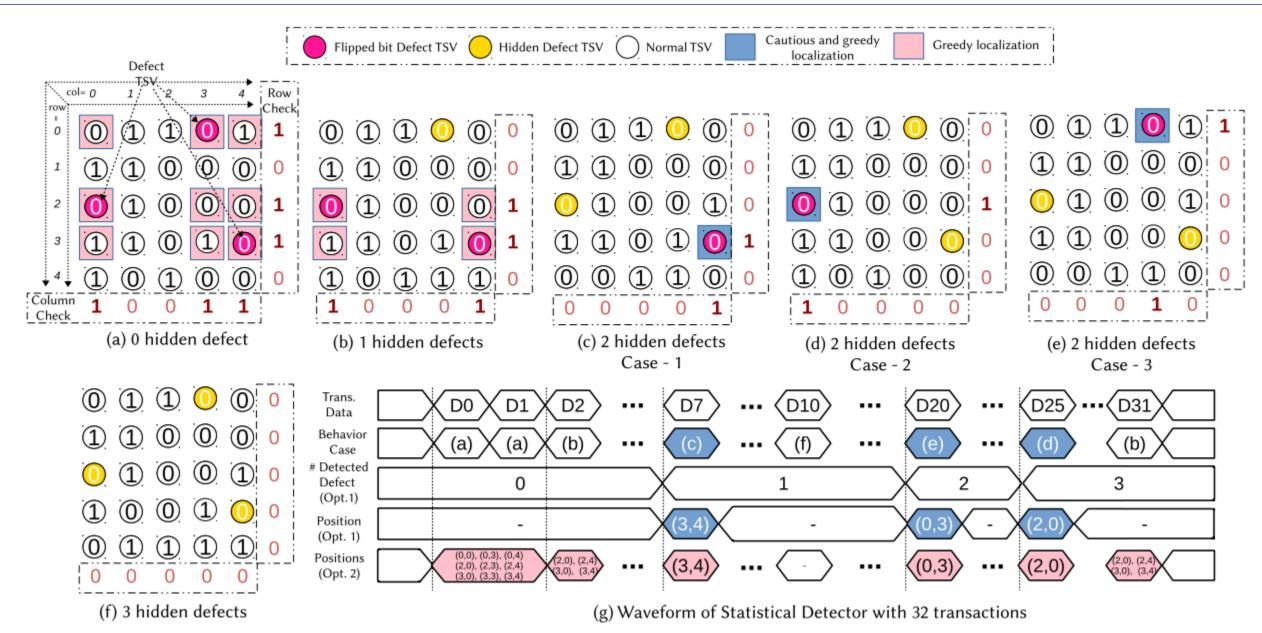






## Statistical detection: greedy localization



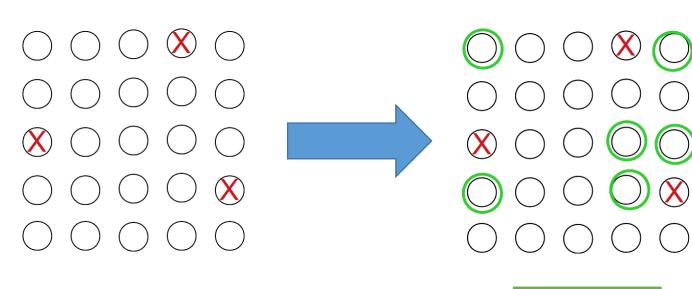


## Statistical detection: Output of greedy localization



Output

- It greedily captures as much as position as possible:
  - They are suspicious TSVs.
- Accuracy
  - Red X: true negative
  - Green circle: false positive
- Since the false positive TSV
- still transfer data:
  - It is not critical
- However:
  - Are there still hidden defects?
  - Is it possible to remove the false positive cases?

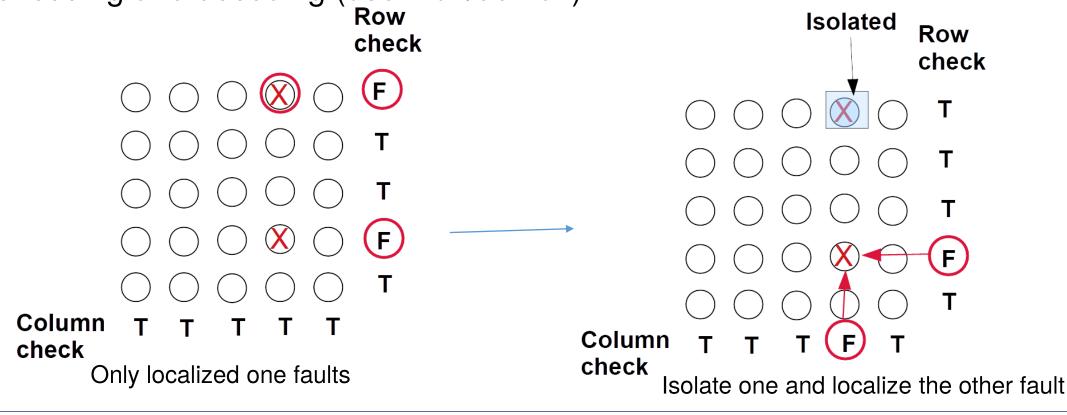


## Isolate-and-Check: keep isolating



- After the statistical detection, we have a set of suspicious positions.
- We "isolate" them:
  - They still transfer data as usual

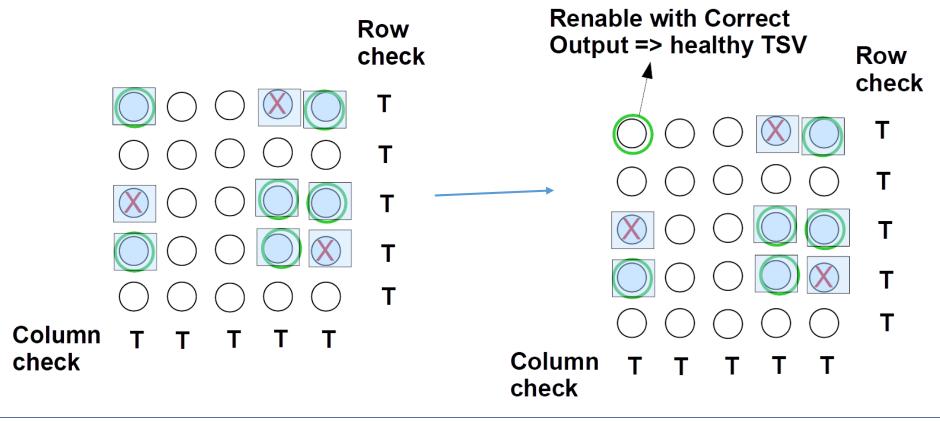
• The ECC (parity product code) do not take consideration of its value: remove it from encoding and decoding (use mux/demux).



## Isolation-and-Check: re-checking



- Re-assign (disable isolation) each suspicious TSV:
  - If the output of ECC shows the suspicious TSV healthy: false positive case
  - If the output of ECC shows the suspicious TSV faulty: true negative case



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## Evaluation methodology

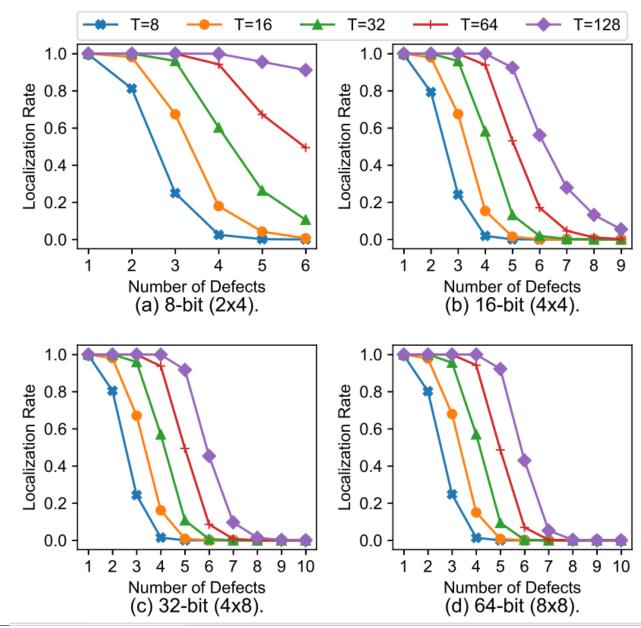


- Design in Verilog HDL
- Design with:
  - NANGATE 45nm and NCSU FreePDK TSV
  - Synopsys Design Compiler
  - Cadence Innovus
- Localization performance:
  - Monte-Carlo simulation with 10,000 tests.
    - For small number of tests, brute-force test is used.

Width	8, 16, 32, and 64-bit
PPC	2x4, 4x4, 4x8, and 8x8
Statistical detection period (T)	8, 16, 32, 64 and 128 cycles
Number of defects	1-6 (2x4) 1-9 (others)
Detect type	Open/short

### Statistical detection: Localization rate w. false positive

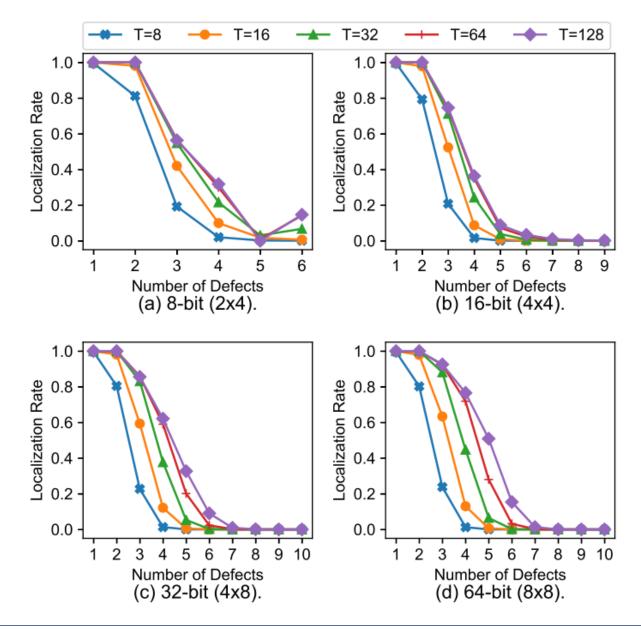




- Thank to the greedy localization, statistical detection could capture 4+ defects in most case:
- However, there are still false positive case:
  - TSV is healthy
  - Statistical detection marks is "suspicious:"

### Statistical detection: Localization rate w/o false positive

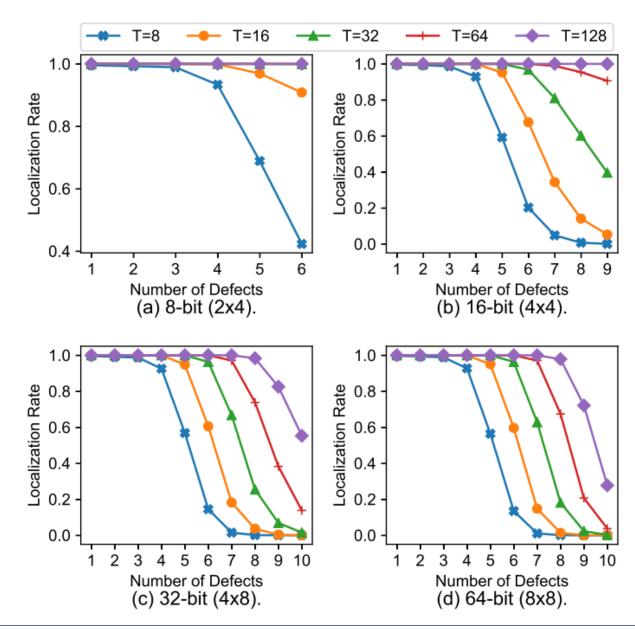




- If we consider false positive as incorrect test result
  - Statistical detection could localize two faults
  - PPC itself only localizes one fault
- This is 2x improvement from statistical detection

### Isolation-and-Check

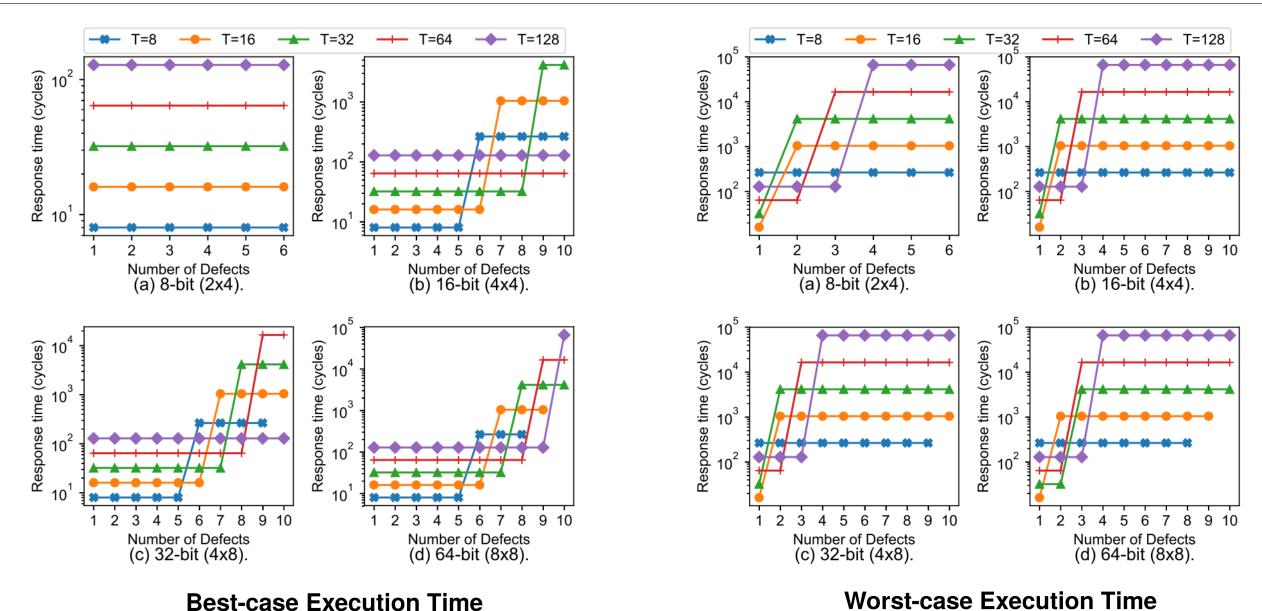




- By re-checking, OCTT remove the false positive cases.
- OCTT could localize up to 100% of 6 cases.
- With 8-9 case, the localization rate is still high (>90%).

### **Execution Time**





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## Hardware complexity



Scheme	Tech. (nm)	k (bit)	n (bit)	Area Cost (µm²)		Latency (ns)		Power (µW)		
	Scheme	Tech. (11111)	K (bit)	H (bit)	Encoder	Decoder	Encoder	Decoder	Encoder	Decoder
Hamming [14]		45	32	39	94.1640	234.8780	0.55	1.12	30.0831	96.2898
SECDED [19]		45	32	40	111.7200	253.7640	0.60	1.44	36.9622	103.1422
SEC-DAEC [30] <sup>1</sup>		45	32	39	322	1902	0.53	1.33	-	-
TAEC [31] <sup>1</sup>		45	32	40	264	2628	0.45	1.32	-	-
	$PPC(4 \times 8)$	45	32	45	76.6080	187.2640	0.30	0.68	43.0272	129.4174
OCTT	Total	45	32	45	130.3400	2161.2500	0.39	0.72	48.639	$1.04 \times 10^{3}$
	$PPC(4 \times 8)$	45	32	45	130.3400	327.4460	-	-	48.639	198.424
	Stat_det	45	32	45	-	751.1840	-	-	-	408.621
	Isol_Check	45	32	45	-	1016.3860	-	-	-	387.056

<sup>&</sup>lt;sup>1</sup> We use the area optimization and lowest area cost design since our design is optimized for area cost.

- Our area cost is significantly higher since we have registers for storing suspicious position.
- However, thank to row/column check, the latency (max frequency) is still promising.

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### Conclusion



- This work presents a non-preemptive and online test for TSV:
  - Statistical detection to capture all possible suspicious TSVs
  - Isolation and check to capture more suspicious TSVs and remove false positive cases.
- The results show that Statistical detection improves 2x the localization rate of the baseline ECC while Isolation and check improves 6x.
- The hardware complexity of this work is reasonable since it could provide high localization rate.
- Future works:
  - Integrate into 3D-Network-on-Chip to study and area/power overhead.
  - Extract the execution time.

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# Thank you for your attention!